

Design optimization for high efficiency induction motor in electro-spindle application

Marco Apuzzo (electrical machine designer)

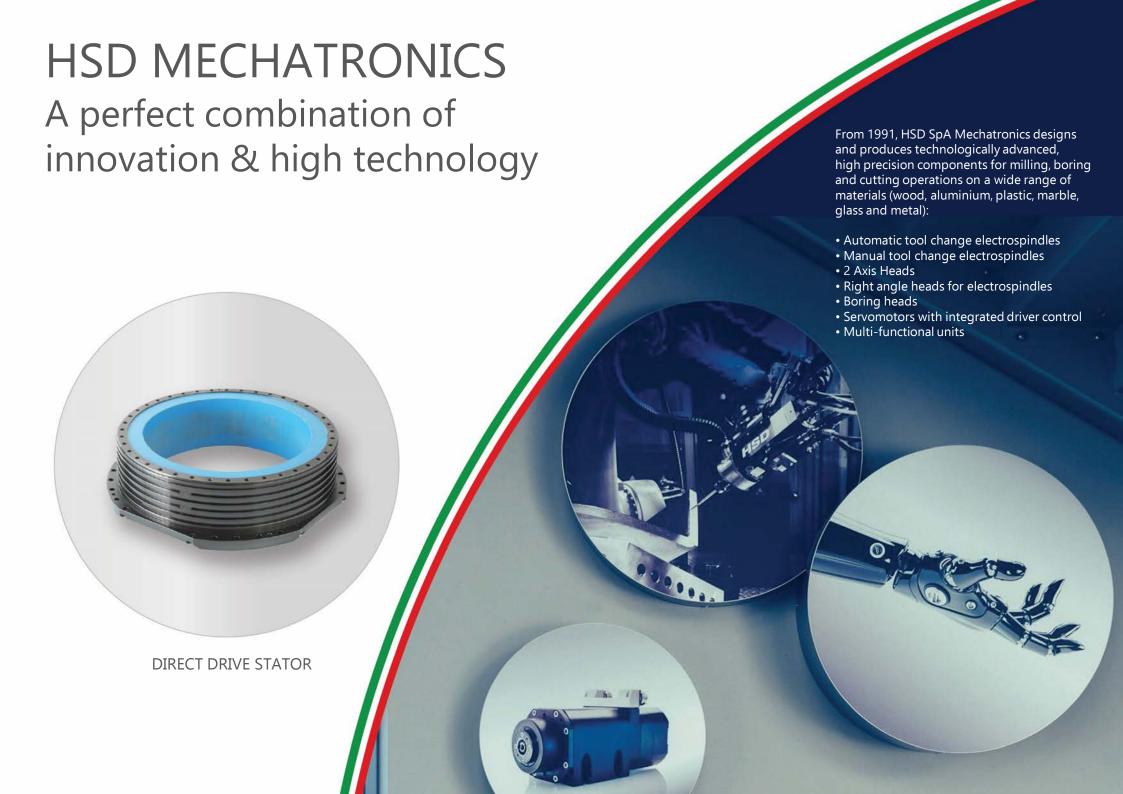
More Value for Your Machine





Part 1 HSD presentation









Product Portfolio (1 of 3): Two-axis head





AUTOMOTIVE

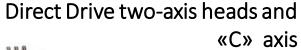


WINDOWS & FURNITURE















«Gear driven» **Direct Drive two-axis heads**



Product Portfolio (2 of 3): Electrospindle









Electrospindles for metal applications

And composite materials











Glass & Stone applications Electrospindles







Wood and Plastic applications Electrospindles



Product Portfolio (3 of 3)







Boring heads, Multifunciton units, aggregates for wood, alluminum, plastic, glass & stone applications











Smart Motors, «Electronic equipment» Rotors & Stators, Direct Drive Motors



Some references















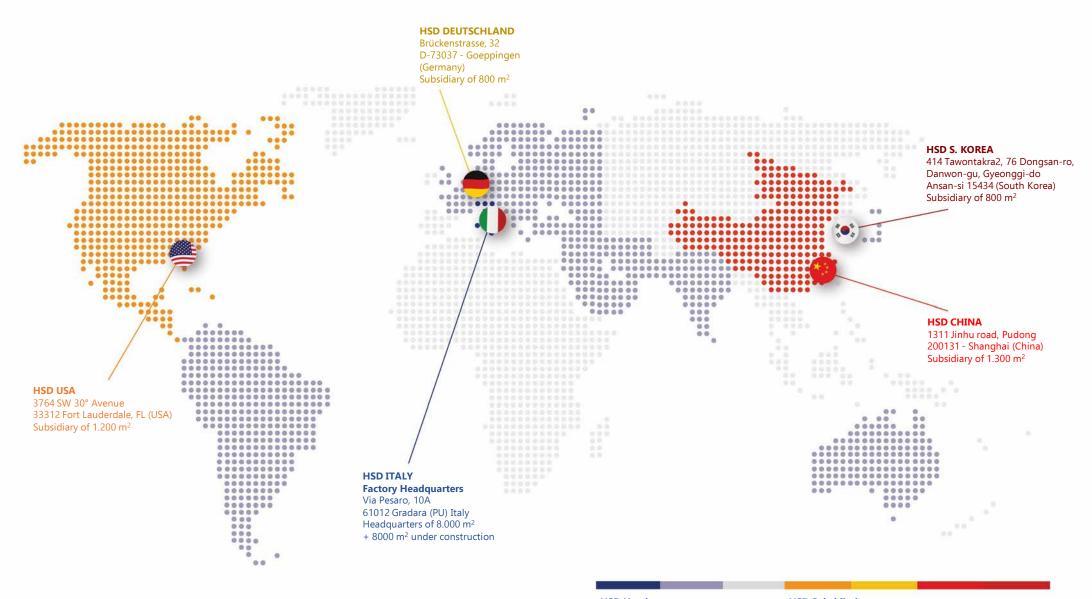






HSD GLOBAL NETWORK

Global network with owned subsidiaries in the main markets in order to provide the customer with immediate and qualified support.









QUALITY & CERTIFICATIONS

HSD has always considered Quality one of its priorities. In the early 90s the company built a Quality Management System based on the highest international standards, gaining today the OHSAS 18001 and ISO 9001:2015 certification. Each model and component, during product development, is subjected to rigorous reliability testing by simulating the hardest working conditions a product could expect to face.









- Certified measuring and testing equipments
- Strict internal processing procedures
- Field technicians periodically updated at the HSD Training LAB
- Subsidiaries Global Network

SHAFT KIT

RESEARCH & DEVELOPMENT



NEW ELECTRONIC SOLUTIONS

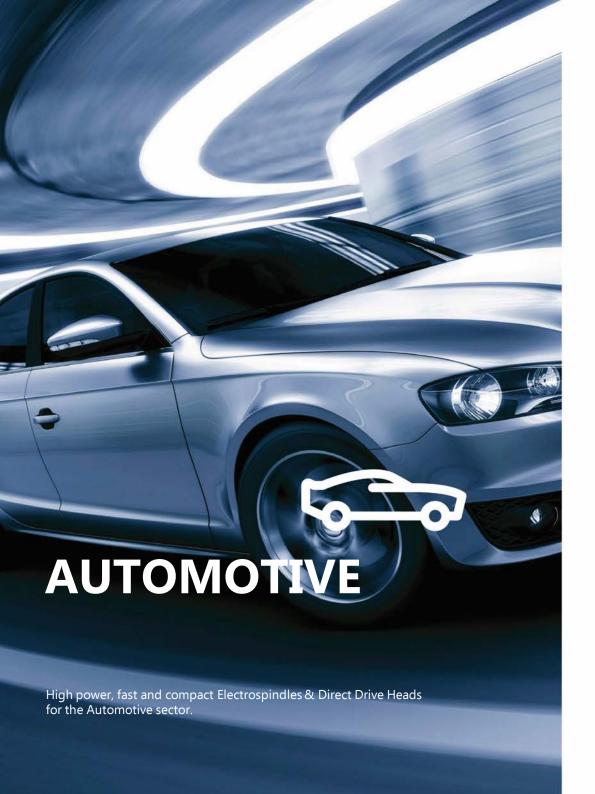


C-CORE Industry 4.0

Technological excellence combines with the integrated development of mechanical and electronic skills both in design, production and quality systems.

DIRECT DRIVE 2 AXIS HEAD











28000rpm Air-oil

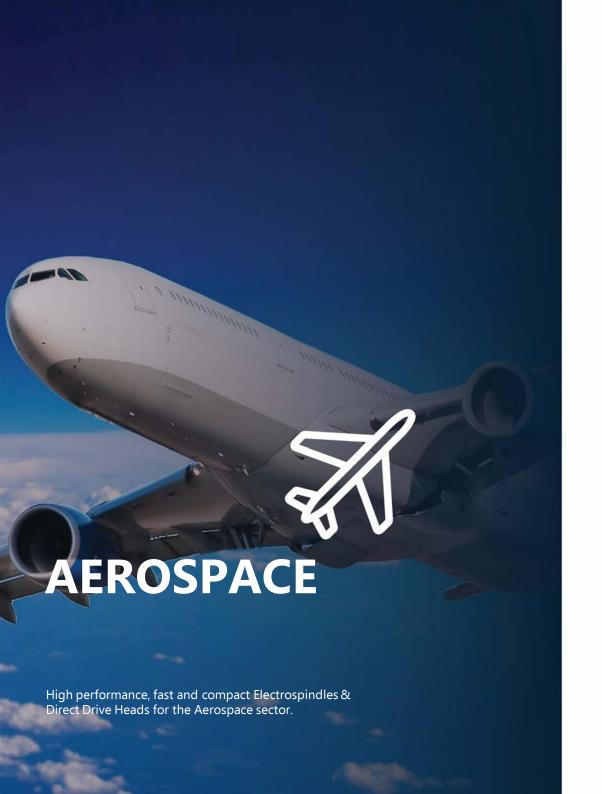
HSK A63/A100 Body Diameter: Ø180mm Torque S1: from 38 to 95,5Nm Power S1: from 24 to 70kW Max Speed: 18000rpm Grease

Max Speed: 24000rpm Grease 32000rpm Air-oil

ES332 HSK A40/E40 Body Diameter:150mm Torque S1:10,3Nm Power S1:13kW

HST610 DIRECT DRIVE DOUBLE SIDED

Max. Speed Axis A;C: °/sec 180;180 Clampling torque Axis brakes A;C:Nm 1800/2000 Weight: Kg 290







HST810 DIRECT DRIVE DOUBLE SIDED

Max. Speed Axis A;C:
°/sec 180;180
Clampling torque Axis brakes A;C:
Nm 4000/4000
Weight: Kg 740



ES550 HSK A63

Body Diameter: Ø210mm Torque S1: 124Nm Power S1: 26kW Max Speed: 18000rpm



Body Diameter: Ø230mm Torque S1: from 34,5 to 170Nm Power S1: from 25 to 100kW Max Speed: from 10000 to 30000rpm



CONSUMER ELECTRONICS

Low vibration, Fast and precise Electrospindles & 2 Axis Heads for the Consumer Electronics sector.





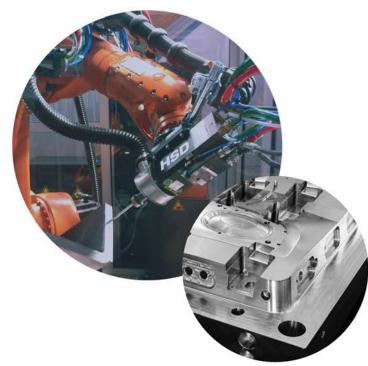


ES327 HSK E25 Body Diameter: Ø80mm Torque S1: 1Nm Power S1: 3kW Max Speed: 50000rpm

HST570 DIRECT DRIVE

Max. Speed Axis A;C: °/sec 180;180 Clampling torque Axis brakes A;C: 342/342 Nm Weight: Kg 150







ES334 **BT30/HSK E40** Body Diameter: Ø120mm Torque S1: 5,7Nm Power S1: 3,6kW Max Speed: 30000rpm



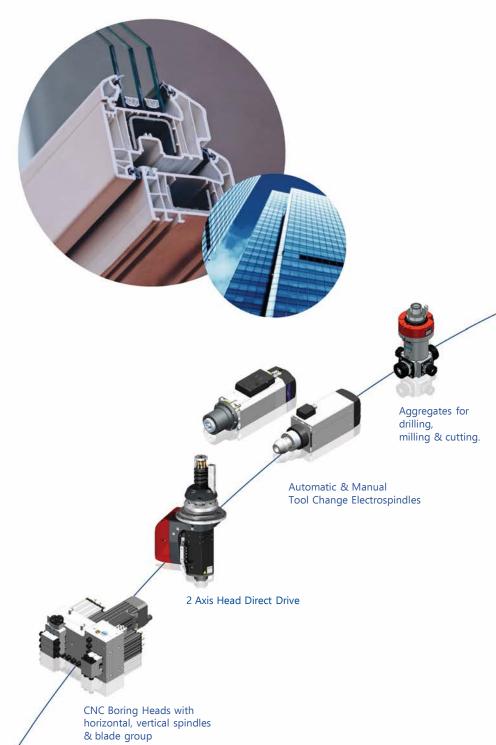
Power S1: from 6,5 to 11kW Torque S1: from 3,4 to 8,7Nm Max Speed: from 20000 to 36000rpm



ES789 HSK F63/A63 Power S1: 25kW

Torque S1: 23,9Nm Max Speed: 24000rpm









Part 2
Design optimization for high efficiency induction motor in electro-spindle application





Customer data input

PERFORMANCE REQUIREMENTS

- 26 kW at 2000÷7500 rpm
- > >200 Nm peak torque
- ➤ Efficiency > 90%
- 10 kW at 18000 rpm
- Drive maximum output frequency ≤ 1200 Hz

OUTLINE REQUIREMENTS

- ➤ Overall Lenght < 800mm
- ➤ Overall Diameter < 220mm
- ➤ Water cooling
- > Thermal class F



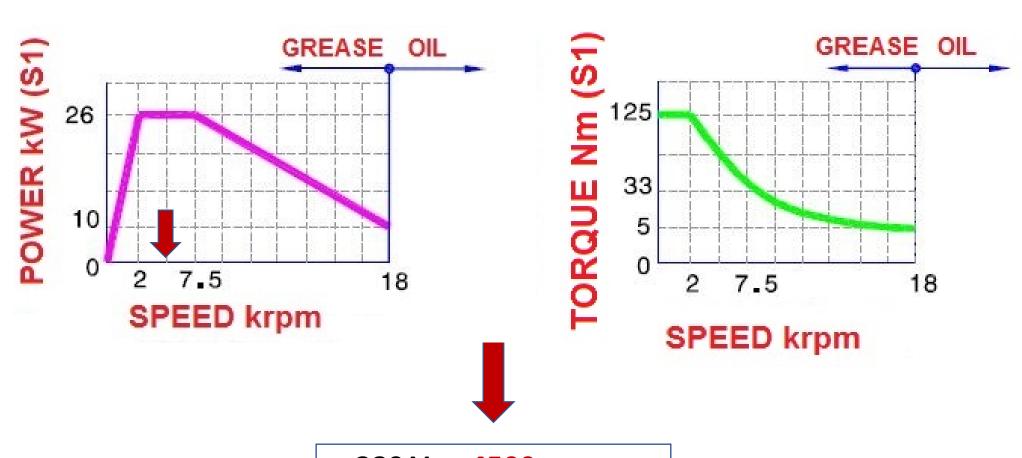
Customer data input – General Scenario

- 1. Estimated annual volume: 10 15 electrospindles
- 2. Market price of 1 electrospindle: below 20,000€
- 3. Time to market: 18-20 weeks

It implies to use standard (NOT CUSTOM MADE) motor geometry design, evaluate the use of the rotor design for other application



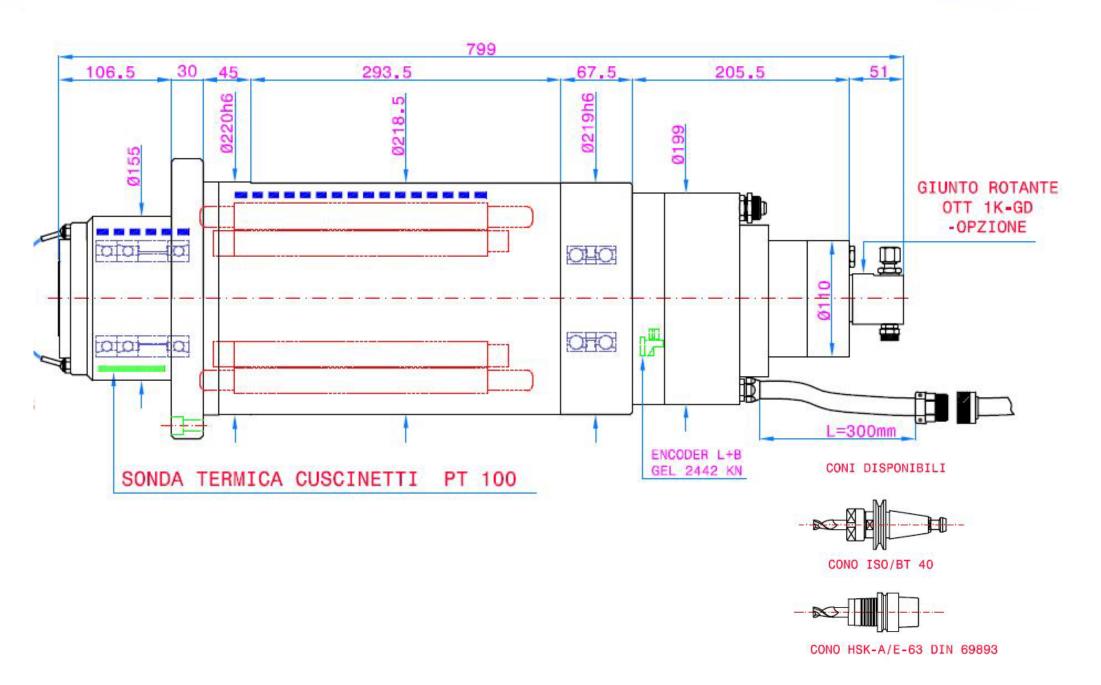
Performance requirements



380 V at 4500 rpm to optimize the efficiency

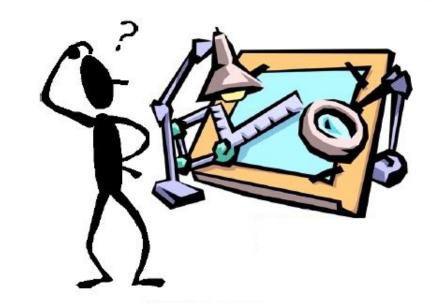
Size constraints

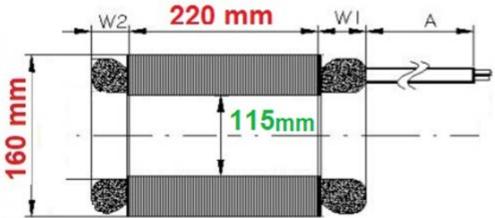






Initial Sizing





- ✓ Poles = 8
- ✓ Peak torque > 200 Nm
- ✓ Possa Formula:

$$\phi \approx 1,3 \ 10^{-3} \ \frac{T_{pk}^{0.55}}{p^{1,1}}$$

$$\phi = B_{max} \cdot \frac{D_{int}L_{stk}}{p}$$

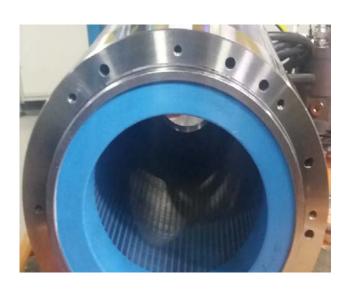
- ✓ Airgap induction: 0.85 T (hp)
- ✓ Fixed the stack lenght to 220 mm
- ✓ Output: Dint ≈ 117 mm

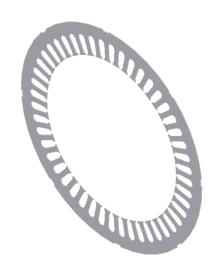


Stator geometry

De	[mm]	160
Di	[mm]	115
Nslot	[-]	48
Poles	[-]	8
Lstk	[mm]	220



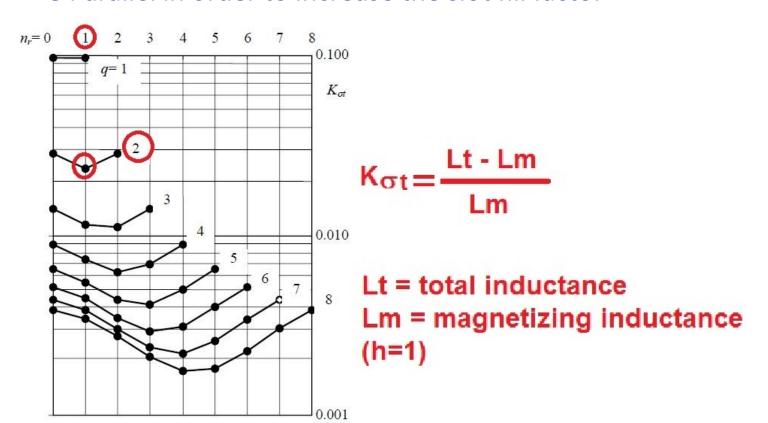




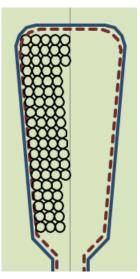


Stator design

- → 3 phase overlap winding with throw 5 → Short pitch winding = 1 (in order to reduce the flux airgap leakage)
- q= 2 slot/pole/phase
- > 8 Parallel in order to increase the slot fill factor



Example of slot fill factor



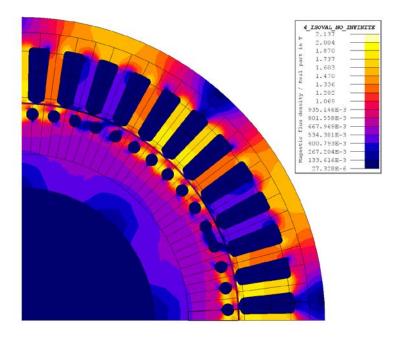


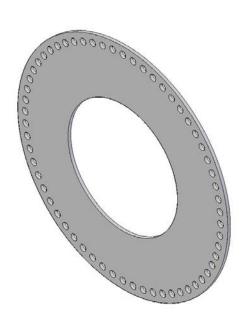
Copper rotor geometry

- Copper conducibilty is higher than Aluminum
- Usually for copper rotor we use round bars

De	[mm]	114.2
Di	[mm]	80
Nslot	[-]	60
Lstk	[mm]	220



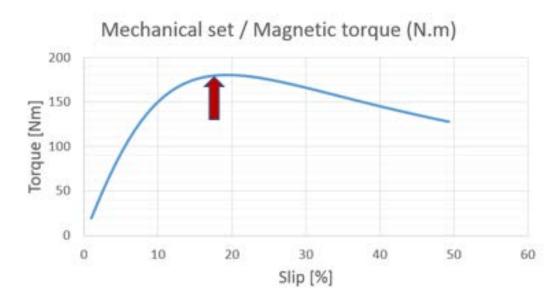






Round bars: results

➤ Peak torque < 200 Nm



Peak torque decreases according to rotating speed in quadratic mode:

$$T_{n_{max}} \sim T_{n_{base}} \left(\frac{n_{base}}{n_{max}} \right)^2$$

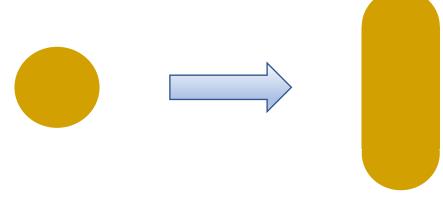
> At 18000 rpm: it could be critical to match the required performance



Rotor geometry optimization

Advantages:

- Bigger slot/copper section
- Low rotor resistance
- Low Joule losses
- Easy of construction
- Useful for different application (like round shape with many combination stator/rotor slots)





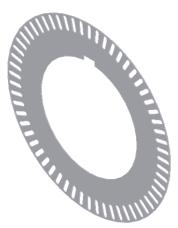


Copper rotor geometry

De	[mm]	114.2
Di	[mm]	80
Nslot	[-]	60
Lstk	[mm]	220



- > 18000 rpm > periph. Speed 107 m/s
- Rotor will require strengthening ring

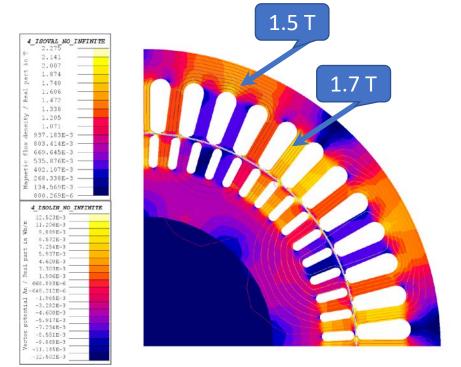


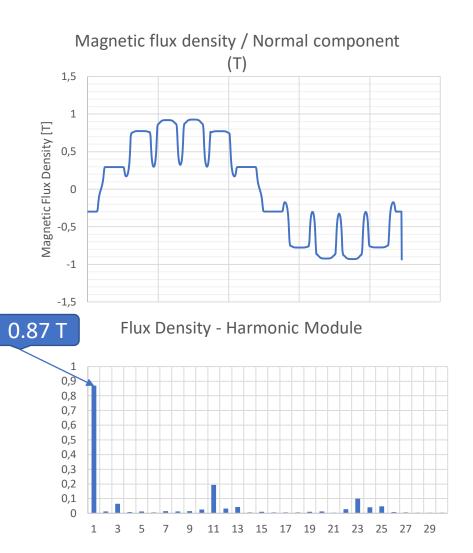




No Load Simulation: FLUX 2D

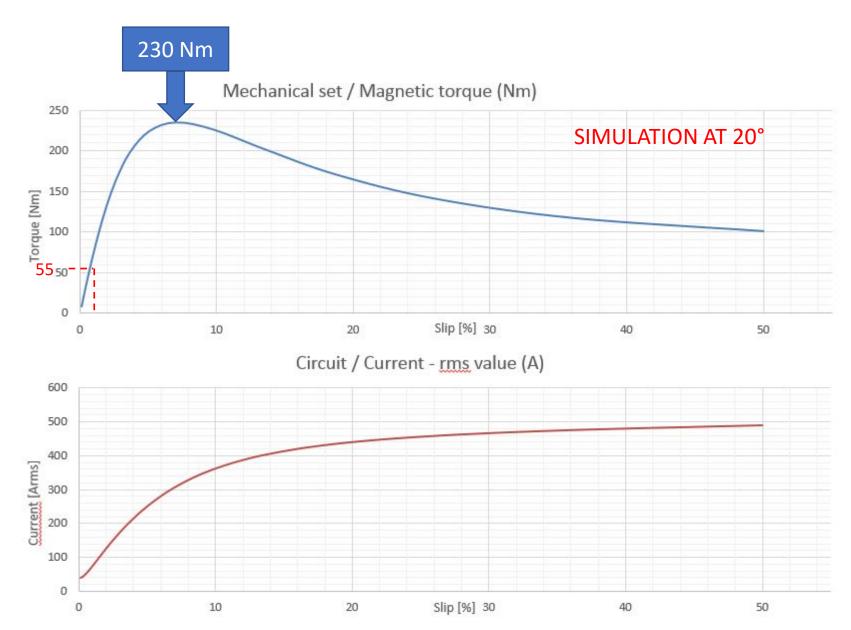
Supply Voltage	[Vrms]	380
Frequency	[Hz]	300
Current	[Arms]	42
Iron Losses	[W]	1485
Lamination	[-]	M330-35A







Load Simulation 300 Hz: FLUX 2D





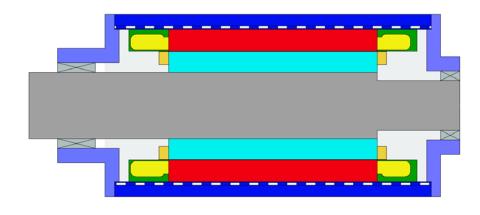
Motor-CAD Simulation

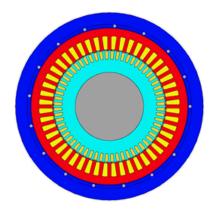
➤ Power loss under load (4500 rpm) by FLUX

Ambient Temperature			
Pj stator	[W]	641	
Pj rotor	[W]	138	
P iron stator	[W]	1467	
P iron rotor	[W]	16	
Total loss	[W]	2262	



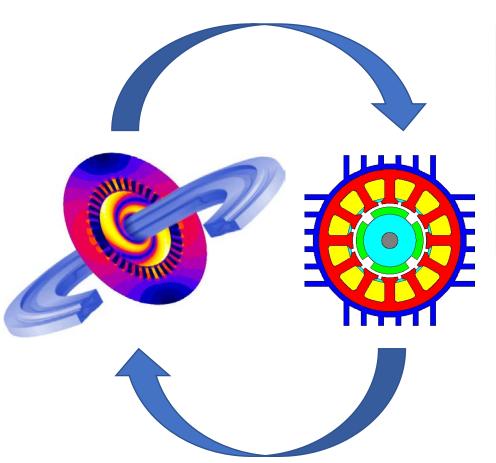
Estimation operating temperature by Motor-CAD







FLUX/MOTORCAD iteration: results

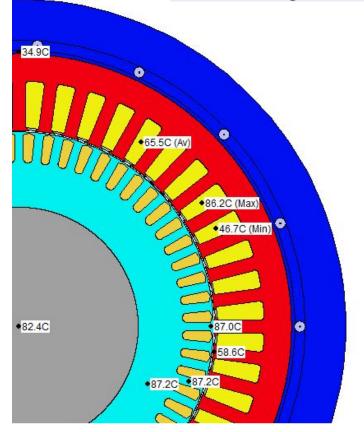


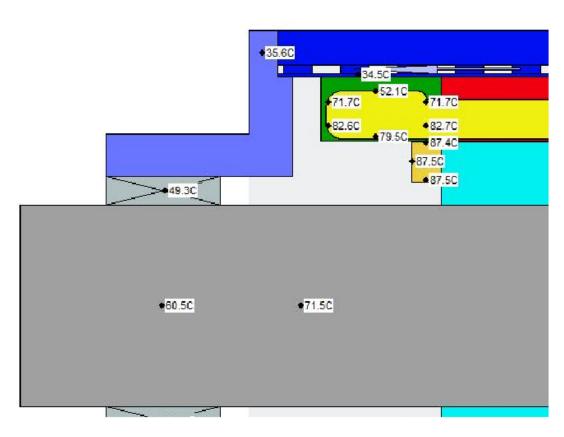
Nominal Power	[kW]	26
Nominal Torque	[Nm]	55.7
Peak Torque	[Nm]	225
Nominal Slip	[%]	0.98
Nominal Current	[Arms]	63
Total loss	[W]	2698
Efficiency	[%]	90.6





Fluid Volume Rate	[l/min]	10
Inlet Temperature	[°C]	25
Outlet Temperature	[°C]	28.9
Winding Temperature	[°C]	66
Winding Time costant	[s]	100
Winding Thermal Resistance	[C/W]	0.015







The «real» Electrospindle



